

Random graphs arising from Strong reinforcement models

Mark Holmes
(Joint work with C. Hirsch and V. Kleptsyn)

December 2017

Motivation

The brain is a graph consisting of neurons (vertices) and synapses (edges).

Motivation

The brain is a graph consisting of neurons (vertices) and synapses (edges).

Neuronal connections that are frequently used become “stronger” (reinforcement).

Motivation

The brain is a graph consisting of neurons (vertices) and synapses (edges).

Neuronal connections that are frequently used become “stronger” (reinforcement).

What kind of “neuronal architectures” can be obtained by simple reinforcement models?

Model 1: WARM process

- ▶ On a graph $G = (V, E)$ of bounded degree, have independent Poisson (rate 1) clock at each vertex.

Model 1: WARM process

- ▶ On a graph $G = (V, E)$ of bounded degree, have independent Poisson (rate 1) clock at each vertex.
- ▶ when clock at $v \in V$ rings, reinforce one of its edges.

Model 1: WARM process

- ▶ On a graph $G = (V, E)$ of bounded degree, have independent Poisson (rate 1) clock at each vertex.
- ▶ when clock at $v \in V$ rings, reinforce one of its edges. The probability of selecting $e \sim v$ is

$$\frac{(N_t(e))^\alpha}{\sum_{e' \sim v} (N_t(e'))^\alpha},$$

Model 1: WARM process

- ▶ On a graph $G = (V, E)$ of bounded degree, have independent Poisson (rate 1) clock at each vertex.
- ▶ when clock at $v \in V$ rings, reinforce one of its edges. The probability of selecting $e \sim v$ is

$$\frac{(N_t(e))^\alpha}{\sum_{e' \sim v} (N_t(e'))^\alpha},$$

where $N_t(e)$ is the number of times (+1) that edge e has been selected previously.

Model 1: WARM process

- ▶ On a graph $G = (V, E)$ of bounded degree, have independent Poisson (rate 1) clock at each vertex.
- ▶ when clock at $v \in V$ rings, reinforce one of its edges. The probability of selecting $e \sim v$ is

$$\frac{(N_t(e))^\alpha}{\sum_{e' \sim v} (N_t(e'))^\alpha},$$

where $N_t(e)$ is the number of times (+1) that edge e has been selected previously. Start with $N_0(e) = 1$ for each e .

Model 1: WARM process

- ▶ On a graph $G = (V, E)$ of bounded degree, have independent Poisson (rate 1) clock at each vertex.
- ▶ when clock at $v \in V$ rings, reinforce one of its edges. The probability of selecting $e \sim v$ is

$$\frac{(N_t(e))^\alpha}{\sum_{e' \sim v} (N_t(e'))^\alpha},$$

where $N_t(e)$ is the number of times (+1) that edge e has been selected previously. Start with $N_0(e) = 1$ for each e .

- ▶ $\alpha > 1$

Model 1: WARM process

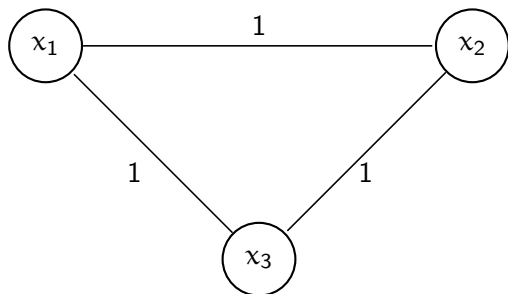
- ▶ On a graph $G = (V, E)$ of bounded degree, have independent Poisson (rate 1) clock at each vertex.
- ▶ when clock at $v \in V$ rings, reinforce one of its edges. The probability of selecting $e \sim v$ is

$$\frac{(N_t(e))^\alpha}{\sum_{e' \sim v} (N_t(e'))^\alpha},$$

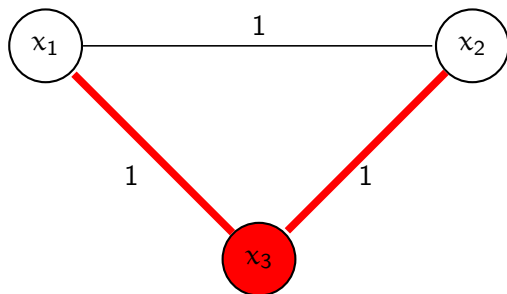
where $N_t(e)$ is the number of times (+1) that edge e has been selected previously. Start with $N_0(e) = 1$ for each e .

- ▶ $\alpha > 1$
- ▶ Interested e.g. in the (random) subset \mathcal{E} of edges used infinitely often/a positive proportion of the time.

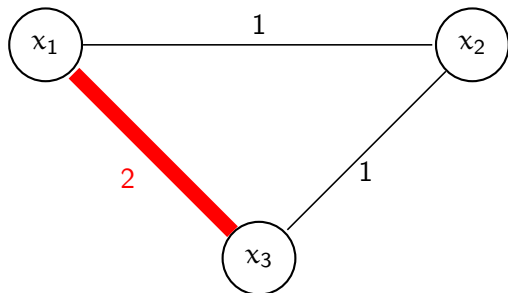
Example: triangle



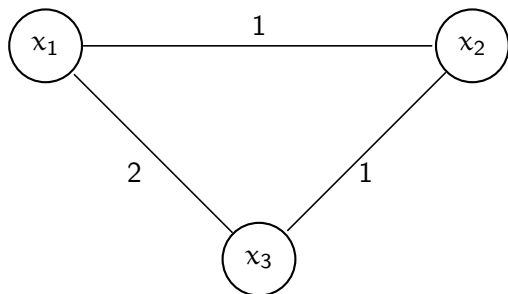
Example: triangle



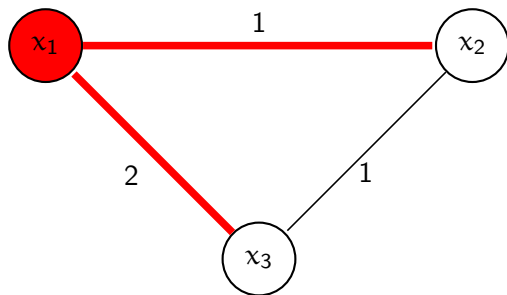
Example: triangle



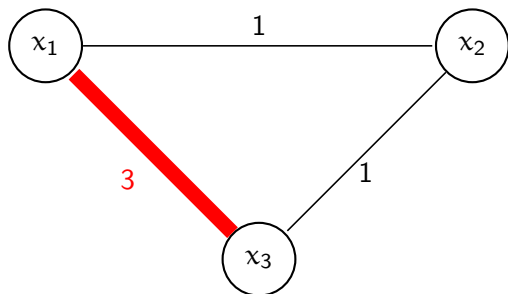
Example: triangle



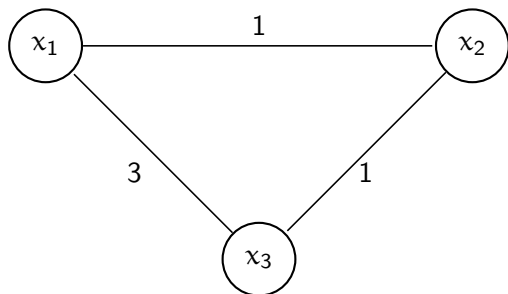
Example: triangle



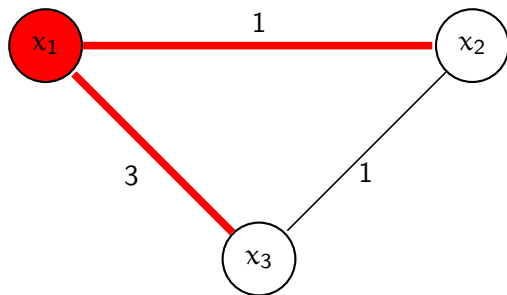
Example: triangle



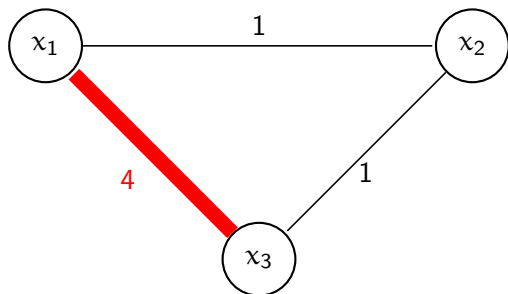
Example: triangle



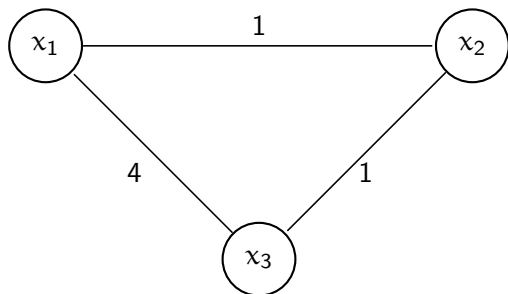
Example: triangle



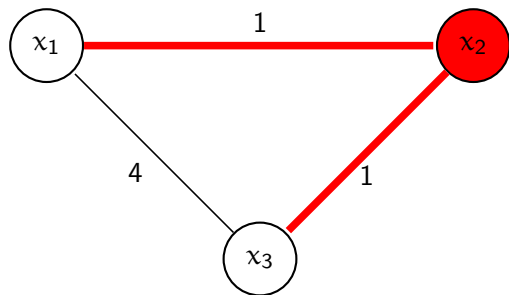
Example: triangle



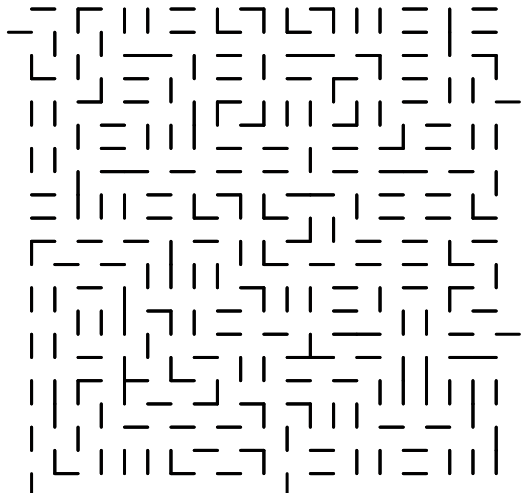
Example: triangle



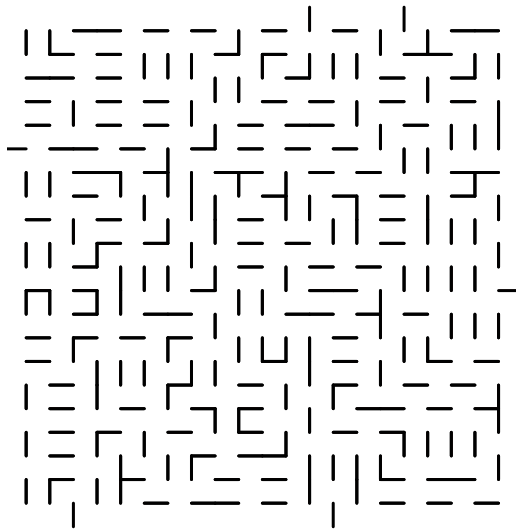
Example: triangle



Example: \mathbb{Z}^2 , $\alpha = 1.9$



Example: \mathbb{Z}^2 , $\alpha = 10$



Finite graphs

- Poisson clocks with common rate 1 equivalent to choosing a vertex uniformly at random.

Finite graphs

- Poisson clocks with common rate 1 equivalent to choosing a vertices uniformly at random.
- Log run behaviour of $(t^{-1}N_t(e))_{e \in E}$ intimately related to deterministic dynamical system describing the *average/expected* dynamics.

Finite graphs

- Poisson clocks with common rate 1 equivalent to choosing a vertices uniformly at random.
- Log run behaviour of $(t^{-1}N_t(e))_{e \in E}$ intimately related to deterministic dynamical system describing the *average/expected* dynamics.
- Morally - the possible limit points for the random process are the stable (or critical) equilibria of the deterministic system (Hard!!!)

Finite graphs

- Poisson clocks with common rate 1 equivalent to choosing a vertices uniformly at random.
- Log run behaviour of $(t^{-1}N_t(e))_{e \in E}$ intimately related to deterministic dynamical system describing the *average/expected* dynamics.
- Morally - the possible limit points for the random process are the stable (or critical) equilibria of the deterministic system (Hard!!!)

$\vec{x} = (x_1, \dots, x_{|E|})$ is an *equilibrium* (/fixed point) if $\forall i \in E$

Finite graphs

- Poisson clocks with common rate 1 equivalent to choosing a vertices uniformly at random.
- Log run behaviour of $(t^{-1}\mathbf{N}_t(e))_{e \in E}$ intimately related to deterministic dynamical system describing the *average/expected* dynamics.
- Morally - the possible limit points for the random process are the stable (or critical) equilibria of the deterministic system (Hard!!!)

$\vec{x} = (x_1, \dots, x_{|E|})$ is an *equilibrium* (/fixed point) if $\forall i \in E$

$$0 = F(\vec{x})_i := -x_i + \sum_{A \ni i} \frac{1}{|V|} \frac{x_i^\alpha}{\sum_{j \in A} x_j^\alpha}.$$

Finite graphs

- Poisson clocks with common rate 1 equivalent to choosing a vertices uniformly at random.
- Log run behaviour of $(t^{-1}\mathbf{N}_t(e))_{e \in E}$ intimately related to deterministic dynamical system describing the *average/expected* dynamics.
- Morally - the possible limit points for the random process are the stable (or critical) equilibria of the deterministic system (Hard!!!)

$\vec{x} = (x_1, \dots, x_{|E|})$ is an *equilibrium* (/fixed point) if $\forall i \in E$

$$0 = F(\vec{x})_i := -x_i + \sum_{A \ni i} \frac{1}{|V|} \frac{x_i^\alpha}{\sum_{j \in A} x_j^\alpha}.$$

v.d.Hofstad, H., Kuznetsov, Ruszel (2016), Basu and Benaim (??),
H. Kleptsyn (2017), Hirsch, H. Kleptsyn (??)

Some theorems (finite G)

Theorem: (H. & Kleptsyn (2017)) For G finite, if $\alpha > 24$ then all stable equilibria are supported on whisker forests (connected components are trees of diameter at most 3).

Some theorems (finite G)

Theorem: (H. & Kleptsyn (2017)) For G finite, if $\alpha > 24$ then all stable equilibria are supported on whisker forests (connected components are trees of diameter at most 3).

(e.g. if G is the triangle then $\mathcal{E} \neq E$ as soon as $\alpha > 4/3$).

Some theorems (finite G)

Theorem: (H. & Kleptsyn (2017)) For G finite, if $\alpha > 24$ then all stable equilibria are supported on whisker forests (connected components are trees of diameter at most 3).

(e.g. if G is the triangle then $\mathcal{E} \neq E$ as soon as $\alpha > 4/3$).

Theorem: (Hirsch, H., & Kleptsyn) No stable equilibrium on G contains an even cycle.

Some theorems (finite G)

Theorem: (H. & Kleptsyn (2017)) For G finite, if $\alpha > 24$ then all stable equilibria are supported on whisker forests (connected components are trees of diameter at most 3).

(e.g. if G is the triangle then $\mathcal{E} \neq E$ as soon as $\alpha > 4/3$).

Theorem: (Hirsch, H., & Kleptsyn) No stable equilibrium on G contains an even cycle.

Theorem: (v.d.Hofstad, H., Kuznetsov, Ruszel) Any odd cycle becomes stable by taking α sufficiently close to 1.

Infinite graphs (Hirsch, H. Kleptsyn)

Theorem: Let $G = (V, E)$ be of bounded degree d .

Infinite graphs (Hirsch, H. Kleptsyn)

Theorem: Let $G = (V, E)$ be of bounded degree d . Then there exists $\alpha_d > 1$ such that for $\alpha > \alpha_d$,

Infinite graphs (Hirsch, H. Kleptsyn)

Theorem: Let $G = (V, E)$ be of bounded degree d . Then there exists $\alpha_d > 1$ such that for $\alpha > \alpha_d$, the connected components of \mathcal{E} are a.s. finite.

Infinite graphs (Hirsch, H. Kleptsyn)

Theorem: Let $G = (V, E)$ be of bounded degree d . Then there exists $\alpha_d > 1$ such that for $\alpha > \alpha_d$, the connected components of \mathcal{E} are a.s. finite.

Theorem: If $G = \mathbb{Z}$ then:

- ▶ For every $\alpha > 1$ connected components of \mathcal{E} are finite a.s.

Infinite graphs (Hirsch, H. Kleptsyn)

Theorem: Let $G = (V, E)$ be of bounded degree d . Then there exists $\alpha_d > 1$ such that for $\alpha > \alpha_d$, the connected components of \mathcal{E} are a.s. finite.

Theorem: If $G = \mathbb{Z}$ then:

- ▶ For every $\alpha > 1$ connected components of \mathcal{E} are finite a.s.
- ▶ there exists $\alpha_* \approx 4.4$ such that

Infinite graphs (Hirsch, H. Kleptsyn)

Theorem: Let $G = (V, E)$ be of bounded degree d . Then there exists $\alpha_d > 1$ such that for $\alpha > \alpha_d$, the connected components of \mathcal{E} are a.s. finite.

Theorem: If $G = \mathbb{Z}$ then:

- ▶ For every $\alpha > 1$ connected components of \mathcal{E} are finite a.s.
- ▶ there exists $\alpha_* \approx 4.4$ such that the connected components of \mathcal{E} are of length
 - (a) 1, 2 for $\alpha \in (2, \alpha^*)$,

Infinite graphs (Hirsch, H. Kleptsyn)

Theorem: Let $G = (V, E)$ be of bounded degree d . Then there exists $\alpha_d > 1$ such that for $\alpha > \alpha_d$, the connected components of \mathcal{E} are a.s. finite.

Theorem: If $G = \mathbb{Z}$ then:

- ▶ For every $\alpha > 1$ connected components of \mathcal{E} are finite a.s.
- ▶ there exists $\alpha_* \approx 4.4$ such that the connected components of \mathcal{E} are of length
 - 1, 2 for $\alpha \in (2, \alpha^*)$,
 - 1, 2, 3 for $\alpha > \alpha^*$.

Infinite graphs (Hirsch, H. Kleptsyn)

Theorem: Let $G = (V, E)$ be of bounded degree d . Then there exists $\alpha_d > 1$ such that for $\alpha > \alpha_d$, the connected components of \mathcal{E} are a.s. finite.

Theorem: If $G = \mathbb{Z}$ then:

- ▶ For every $\alpha > 1$ connected components of \mathcal{E} are finite a.s.
- ▶ there exists $\alpha_* \approx 4.4$ such that the connected components of \mathcal{E} are of length
 - 1, 2 for $\alpha \in (2, \alpha^*)$,
 - 1, 2, 3 for $\alpha > \alpha^*$.

Moreover, any even length is possible by taking α sufficiently close to 1.

Infinite graphs - general approach:

- ▶ Let \mathcal{N} denote the set of edges that are never chosen by the process.

Infinite graphs - general approach:

- ▶ Let \mathcal{N} denote the set of edges that are never chosen by the process.
- ▶ Show (via coupling argument) that \mathcal{N}^c does not percolate (components of \mathcal{N}^c are finite).

Infinite graphs - general approach:

- ▶ Let \mathcal{N} denote the set of edges that are never chosen by the process.
- ▶ Show (via coupling argument) that \mathcal{N}^c does not percolate (components of \mathcal{N}^c are finite).
- ▶ Process behaves independently on distinct components of \mathcal{N}^c .

Infinite graphs - general approach:

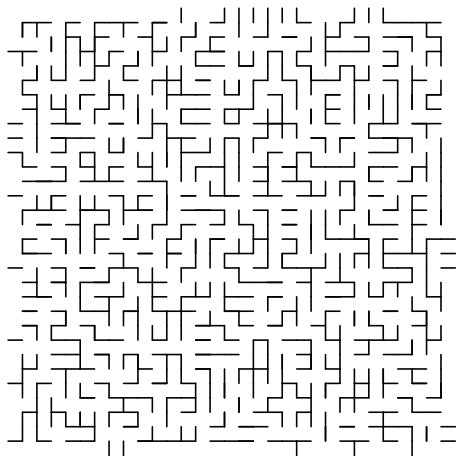
- ▶ Let \mathcal{N} denote the set of edges that are never chosen by the process.
- ▶ Show (via coupling argument) that \mathcal{N}^c does not percolate (components of \mathcal{N}^c are finite).
- ▶ Process behaves independently on distinct components of \mathcal{N}^c .
- ▶ Process on a finite component F behaves *similarly to* WARM process on the graph F itself.

Bounded degree: Compass model

On graph G , independently from each vertex colour in an incident edge uniformly at random.

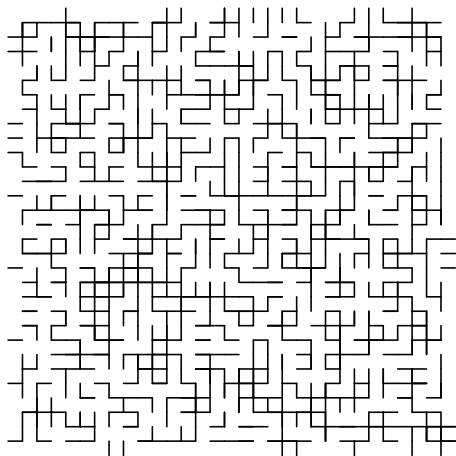
Bounded degree: Compass model

On graph G , independently from each vertex colour in an incident edge uniformly at random.



Bounded degree: Corrupt compass model

Now independently (at each vertex) with probability ε colour in all incident edges.



Bounded degree:

- Prove that connected clusters in Corrupted compass model are finite for ε sufficiently small.

Bounded degree:

- Prove that connected clusters in Corrupted compass model are finite for ε sufficiently small.
- Couple \mathcal{N}^c with the above set (with α large enabling ε small) so that components of \mathcal{N}^c are finite.

Bounded degree:

- Prove that connected clusters in Corrupted compass model are finite for ε sufficiently small.
- Couple \mathcal{N}^c with the above set (with α large enabling ε small) so that components of \mathcal{N}^c are finite.
- Once components of \mathcal{N}^c are finite they are behaving like* finite components of a finite graph.

Facts about \mathbb{Z}^2

- On the square lattice, no finite component of \mathcal{E} contains an even cycle for any $\alpha > 1$.

Facts about \mathbb{Z}^2

- On the square lattice, no finite component of \mathcal{E} contains an even cycle for any $\alpha > 1$.
- ▲ On the triangular lattice, you see cycles of odd length n if $\alpha < \frac{2}{1 - \cos(\pi(1 + (1/n)))}$.

Model 2.0: Strongly reinforced RW

- ▶ Vertex selections no longer i.i.d. according to Poisson clocks.

Model 2.0: Strongly reinforced RW

- ▶ Vertex selections no longer i.i.d. according to Poisson clocks.
- ▶ Instead, start with vertex 0, and whenever you choose an edge incident to the current vertex, walk across it to get to your next vertex.

Model 2.0: Strongly reinforced RW

- ▶ Vertex selections no longer i.i.d. according to Poisson clocks.
- ▶ Instead, start with vertex 0, and whenever you choose an edge incident to the current vertex, walk across it to get to your next vertex.
- ▶ This defines a (strongly) reinforced random walk.

Model 2.0: Strongly reinforced RW

- ▶ Vertex selections no longer i.i.d. according to Poisson clocks.
- ▶ Instead, start with vertex 0, and whenever you choose an edge incident to the current vertex, walk across it to get to your next vertex.
- ▶ This defines a (strongly) reinforced random walk. Since $\alpha > 1$ the walk gets stuck on a single edge. (Limic, Limic & Tarres, Cotar & Thacker etc.)

Model 2.0: Strongly reinforced RW

- ▶ Vertex selections no longer i.i.d. according to Poisson clocks.
- ▶ Instead, start with vertex 0, and whenever you choose an edge incident to the current vertex, walk across it to get to your next vertex.
- ▶ This defines a (strongly) reinforced random walk. Since $\alpha > 1$ the walk gets stuck on a single edge. (Limic, Limic & Tarres, Cotar & Thacker etc.)
- ▶ Can force the walker to not get stuck on a single edge by never allowing it to backtrack.

Model 2.1: SRNBRW

Work in progress with Victor Kleptsyn (see also Le Goff and Raimond).

Model 2.1: SRNBRW

Work in progress with Victor Kleptsyn (see also Le Goff and Raimond).

On a graph of bounded degree:

Model 2.1: SRNBRW

Work in progress with Victor Kleptsyn (see also Le Goff and Raimond).

On a graph of bounded degree:

True Conjecture: For $\alpha \gg 1$ the walker gets stuck on either a single loop, or two loops joined by a path.

Model 2.1: SRNBRW

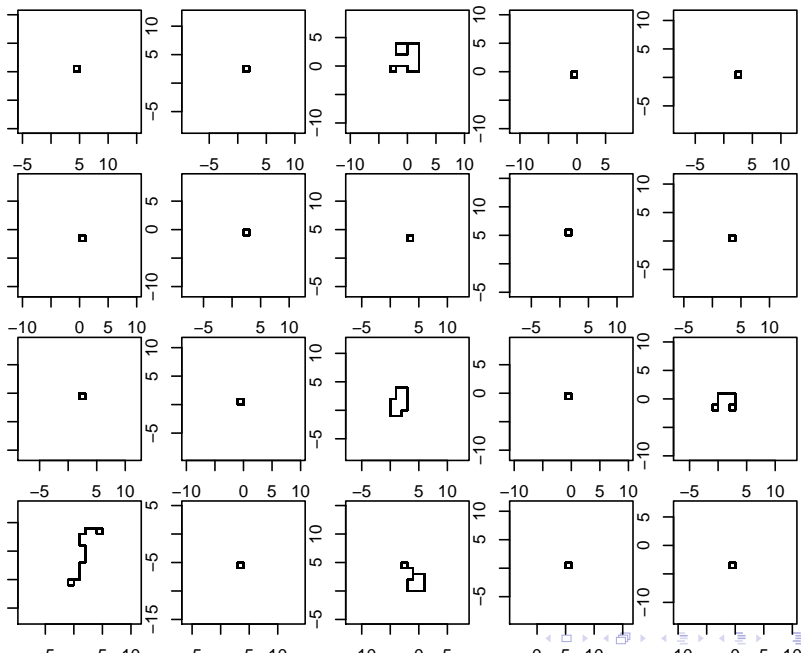
Work in progress with Victor Kleptsyn (see also Le Goff and Raimond).

On a graph of bounded degree:

True Conjecture: For $\alpha \gg 1$ the walker gets stuck on either a single loop, or two loops joined by a path.

Q: Is there any finite graph (without leaves) on which the walker cannot get stuck for every $\alpha > 1$?

Simulations - $\alpha = 10$



Thanks!

Thanks!